

# Java Programming II

## Lab9

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514770-1

Fall 2024

11/27/2024

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# Lab9

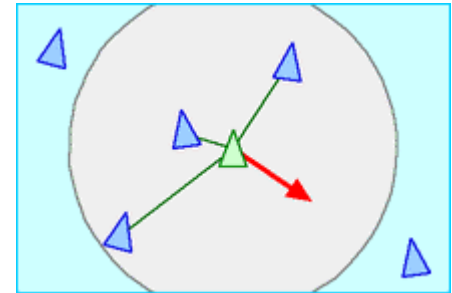
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- Practice to write a program that **Flocking of Birds (Boids)** change its **State** based on its position and direction of their nearby neighbors using **State pattern**.
  - **BoidState<T> interface**
  - **WanderState, CohesionState, AlignmentState, SeperationState**

# Lab9

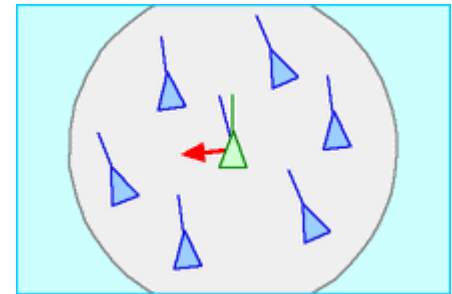
## □ Separation

- Separation is a rule to **move away from nearby neighbors** to avoid crowding objects around them.



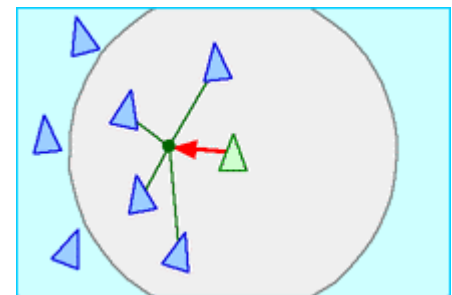
## □ Alignment

- Alignment is a rule to **move toward the average direction** of neighboring objects



## □ Cohesion

- Cohesion is a rule to find the midpoint (Average Position) between all neighbors and **move towards the midpoint**.

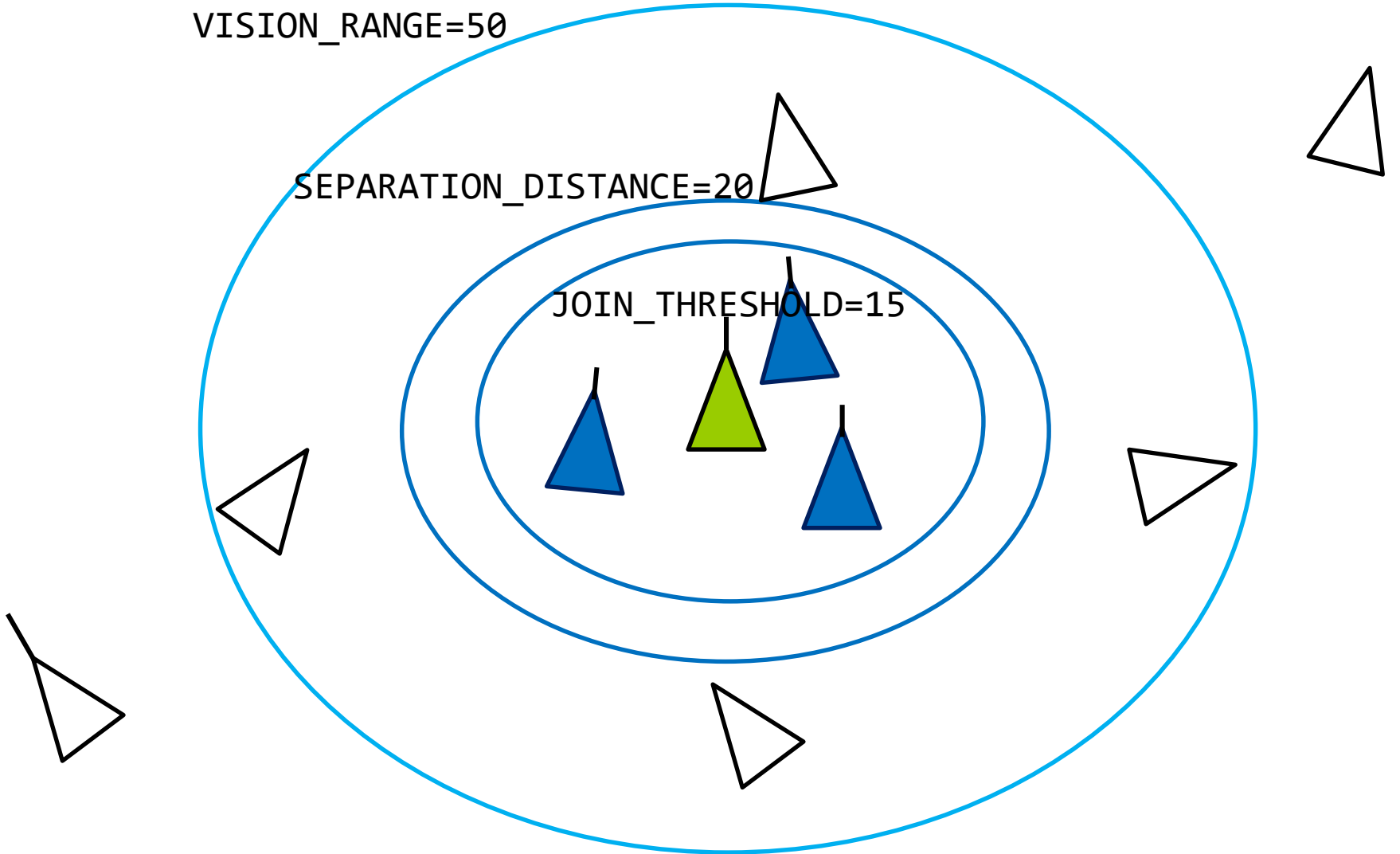


# Lab9

VISION\_RANGE=50

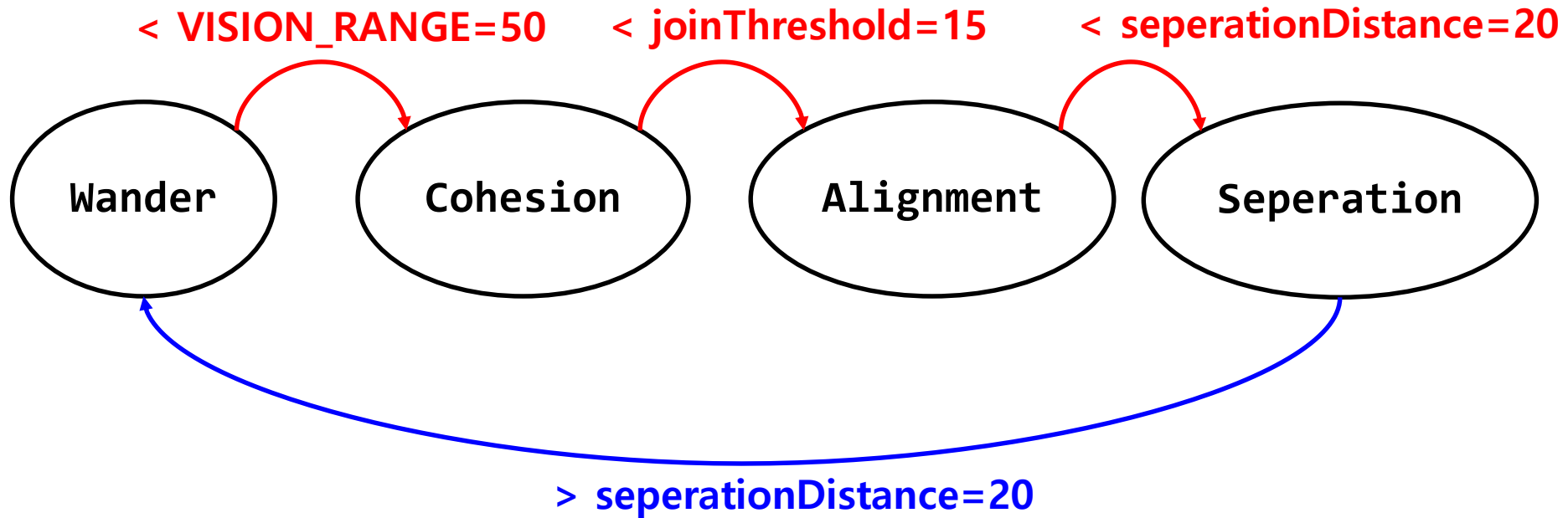
SEPARATION\_DISTANCE=20

JOIN\_THRESHOLD=15



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## □ BoidState Finite State Machine(FSM)



# Lab9

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## □ WanderState

- Boid **moves randomly**
- State transits to **CohesionState** if any nearby **neighbors** are found, i.e.,  $\text{boid.distance}(\text{other}) < \text{VISION\_RANGE}$

## □ CohesionState

- Boid **moves towards the center (Average Position)** of all **neighbors** ( $< \text{VISION\_RANGE}$ )
- State transits to **AlignmentState** if boid is close enough to midpoint, i.e.,  $\text{boid.distance}(\text{center}) < \text{JOIN\_THRESHOLD}$

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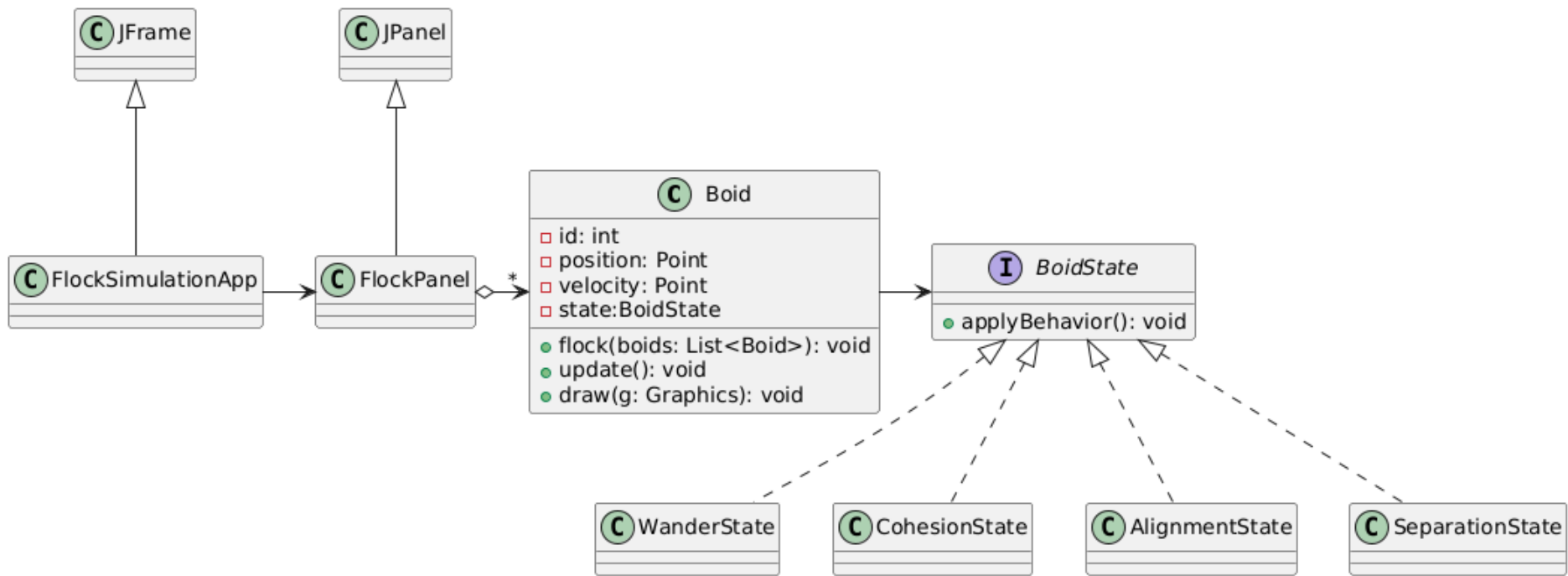
## □ AlignmentState

- Boid **moves towards the average direction (Average Velocity)** of all neighbors ( $< \text{VISION\_RANGE}$ )
- State transits to **SeperationState** if boid is close to neighbors, , i.e.,  $\text{boid.distance}(\text{other}) < \text{SEPARATION\_DISTANCE}$

## □ SeparationState

- Boid **moves away from nearby neighbors to avoid crowding**, i.e.,  $\text{boid.distance}(\text{other}) < \text{SEPARATION\_DISTANCE}$
- State transits to **WanderState** if boid is separated from neighbors, , i.e.,  $\text{boid.distance}(\text{other}) > \text{SEPARATION\_DISTANCE}$

# Lab9





# Lab9

```
public interface BoidState {
    void applyBehavior(Boid boid, List<Boid> boids);
}

public class WanderState implements BoidState {
    private static final int MAX_FORCE = 1;

    @Override
    public void applyBehavior(Boid boid, List<Boid> boids) {
        // random wandering behavior
        Random random = new Random();
        int dx = random.nextInt(2 * MAX_FORCE + 1) - MAX_FORCE;
        int dy = random.nextInt(2 * MAX_FORCE + 1) - MAX_FORCE;
        boid.applyForce(new Point(dx, dy));
    }
}
```

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```
        // check for nearby boids to join a flock
        for (Boid other : boids) {
            if (other != boid &&
boid.getPosition().distance(other.getPosition())
< Boid.VISION_RANGE) {
                System.out.println("boid id=" + boid.getId() + "
state=" + boid.getState() + " changed to CohesionState");
                boid.setState(new CohesionState());
                return; // transition to CohesionState if nearby
boids are found
            }
        }
    }
    @Override
    public String toString() {
        return "WanderState";
    }
}
```

# Lab9

```
public class Boid {
    private Point position;
    private Point velocity;
...
    private BoidState state;
    private int id; // id is automatically assigned by count
    private static int count = 0;

    public Boid(int panelWidth, int panelHeight) {
        ...
        this.id = ++count;
        this.state = new WanderState();
    } ...
    @Override
    public String toString() {
        // id, position, velocity, state
    }
}
```

# Submit to e-learning

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- ▣ Add your code (e.g., other class or design pattern, etc) in the Lab9 assignment.
- ▣ Submit the Lab9 assignment (JAVA24-2-Lab9-YourID-YourName.zip including the report) to e-learning due by 12/3.